Shock acoustical waves on linear and non-linear dielectric and flexoelectric materials

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Intersonic shear cracks and fault ruptures

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 $\eta_2$ 

ure 21. Synthetic isochromatic patterns constructed using the steady state velocity weakening cohesive zone model of reference [58].



#### Lattice wave emission from a moving dislocation

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FIG. 15. A dislocation moving with velocity  $\mathbf{v}_d$  emits lattice waves that propagate with group velocity  $\mathbf{v}_g$ . The successively emitted waves with a certain  $\mathbf{k}$  vector leave a line behind the dislocation. The angle between the line and the -x direction is  $\theta$ = tan<sup>-1</sup>[ $v_{gy}/(v_d - v_{gx})$ ].









FIG. 4. (Color) Emitted waves from a moving dislocation with a velocity of  $0.51c_t$  under the applied stress F=0.051G. (a)  $t = 6.36a/c_t$ , (b)  $t = 6.95a/c_t$ , (c)  $t = 37.69a/c_t$ . The meaning of the colors and the contrast are the same as in Fig. 3. The maximum velocity  $v_{\text{max}}$  of the atomic rows is  $0.125c_t$ ,  $0.176c_t$ , and  $0.201c_t$  in the cases (a), (b), and (c), respectively. The position of the dislocation is indicated with a cross.

#### Compressional and shear wakes in a two-dimensional dusty plasma crystal

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FIG. 3. Theoretical dispersion relation for a 2D triangular Yukawa lattice. It has two modes, compressional and shear. The shear wave has less dispersion, i.e.,  $\omega$  is more nearly  $\propto k$  over a wide range of k than the compressional wave. The wave's propagation direction  $\Theta$  is measured with respect to the primitive vector of the lattice. Reproduced from Fig. 3 of Ref. [12].



-0.9

0.0

0.9

#### Motivation – Outline:

- Seismology
- Activation of Faults
- Fracture Mechanics
- Dielectricity combined with flexoelectricity
- Elimination of polarization
- Dynamic anti-plane problem
- Dispersion relation
- Theoretical and FEM analysis
- Nonlinearities and soliton waves



Illustration of induced polarization due to non-uniform bending deformation of a centro-symmetric (non-piezoelectric) material. Krichen and Sharma (2016)



Isotropic anti-plane dielectric flexoelectric:

 $\beta = 0$ 

**Assume:**  $X_z = 0, \Phi_{z} = 0, E_z^0 = 0$ 

$$\mu \nabla^2 u_z - \left(\frac{\mu (b_{44} + b_{77})}{a} - \frac{(e_{44} - f_{12})^2}{a}\right) \nabla^4 u_z = \rho \ddot{u}_z - \frac{(b_{44} + b_{77})}{a} \rho \nabla^2 \ddot{u}_z$$

$$\underbrace{\frac{\mu \ell^2}{2}}_{2}$$

 $\mu > 0, \ a > 0, \ f_{44} > 0, \ e_{44} > 0, \ b_{44} + b_{77} > 0, \ \mu (b_{44} + b_{77}) - e_{44}^2 > 0$ 

$$\frac{\ell^2}{2} = \frac{\left(b_{44} + b_{77}\right) - \left(e_{44} + f_{12}\right)^2 / \mu}{a} > 0$$

$$\frac{H^2}{12} = \frac{\left(b_{44} + b_{77}\right)}{a} > 0$$



Isotropic anti-plane dielectric flexoelectric:  $\beta = 0$ 

Typical material constants (Maraghandi et al., 2006):



#### Isotropic anti-plane dielectric flexoelectric: FEM model



- We model the anti-plane space as a thin plate which extends multiple times the characteristic lengths of the problem.
- The plate's Poisson ratio is set to zero and orthotropic elasticity was tuned to capture the micro-inertia length.
- Pre-stretching was applied according to the crack velocity and the micro-structural length of the problem.
- Only half the space is discretized by 100000 linear quadrilateral elements (S4R in ABAQUS notation) and 600 linear triangular elements (S3 in ABAQUS notation).

#### Contour fields of out of plane displacements: Influence of velocity



### Contour fields of rotations $w_{,2}$ : Influence of velocity



### Contour fields of rotations $w_{,1}$ : Influence of velocity



#### Conclusions:

- Antiplane problems in flexoelectricity
- Couple stress (micro-structural length, microinertia length)
- Prestressed plate analogue and FEM methodology
- Steady state results
- Dispersion analysis
- Facture faults
- Anharmonic elasticity
- Viscosity
- Solitons